

Actuator SQM40.../SQM41...

## Actuators for air and gas dampers

- Electromotoric actuator up to $10 \mathbf{N m}$
- Clockwise and counterclockwise variants
- Running times from 15 and 30 seconds
- Various shaft ends available
- Electronic version with analog control input
- Internal position indication
- Drive shaft can be disengaged
- UL approval

The SQM40...ISQM41... and this Data Sheet are intended for use by OEMs which integrate the actuators in their products!

The SQM40.../SQM41... actuators are suited for driving flow control valves, butterfly valves, dampers or for use on other applications that require rotary motion.
Areas of application are oil and gas burners of medium to higher capacity as well as thermal process plants.

The actuators are used primarily for load-dependent control of the flow of gas, oil and combustion air:

- In connection with 3-position or modulating controllers (e.g. $4 . . .20 \mathrm{~mA}$ ), or
- Directly by burner controls


## To avoid injury to persons, damage to property or the environment, the following

 warning notes must be observed!
## Only qualified personnel may open, interfere with or modify the actuators!

- Read the documentation on the actuators carefully and fully. If not observed, dangerous situations might occur
- All product-related activities (mounting, settings and maintenance) must be performed by qualified and authorized personnel


## Caution!

- Risk of electric shock hazard - to disconnect the actuator from power, it may be necessary to open more than one switch. Before performing maintenance work, the actuator must be disconnected from power
- The electrical connection between the conduit fittings is not made automatically. It must be established on installation site
- The connecting plate is made of plastic and does not provide earthing of the conduit fittings. Earthing must be ensured by adequate washers and wire links
- To provide protection against electric shock hazard, the connecting terminals must have adequate touch protection. Make certain that non-insulated connections or wires cannot be touched
- Each time work has been carried out (mounting, installation, service work, etc.), check to ensure that wiring is in an orderly state
- Fall or shock can adversely affect the safety functions. Such actuators must not be put into operation even if they do not exhibit any damage
- Static charges must be avoided since they can damage the actuator's electronic components when touched.
Recommendation: Use ESD equipment


## Notes on use in North America

- Use of flexible conduit including adequate accessories is mandatory
- Use of copper wiring is mandatory
- All circuits of class 2 must use cables type CL3, CL3R, CL3P or comparable types, OR
All circuits are wired according to class 1 (electrical light or power circuits)
- Ensure that the relevant national safety regulations and notes on standards are complied with
- In geographical areas where DIN regulations apply, the mounting and installation requirements of VDE must be satisfied, especially DIN/VDE 0100, 0550 and DIN/VDE 0722
- Make certain that the actuator is not exposed to direct solar radiation
- Required tightening torques:
- Cover screws: 3.5 Nm
- Connecting cover: 2 Nm

SQM40...


SQM41...


Figure: Note for direction of rotation

- Ensure that the electrical wiring is in compliance with national and local safety regulation
- Make certain that strain relief of the connected cables conforms to the relevant standards (e.g. as per DIN EN 60730 and DIN EN 60335)
- Ensure that spliced wires cannot get into contact with neighboring terminals. Use adequate ferrules
- Unused terminals of the SQM40.../SQM41... must be covered by dummy plugs
- When making the wiring, the AC 120 V or AC 230 V section must be strictly separated from other voltage sections, thus ensuring protection against electric shock hazard
- The mechanical coupling between actuators and controlling elements must be formfitted
- The actuators must always be powered via a prefuse of max. 6,3 AT (as per DIN EN 60127 2/5)
- For the protective earth connection, the housing of all models has a marked earth terminal

Marking of the voltage ranges SQM40...ISQM41...:


Figure: Electrical connection of the SQM40.../SQM41...

## Note

SELV or PELV depends on the safety class of the connected components. In the case of PELV, the relevant component is connected to protective earth.

The mechanical setting facility for the cam switches is physically separated from the connection terminals. When the actuator is disconnected from power, the switches can be adjusted via a scale. The switching points can be changed via adjusting screws. The scale indicates the angles of the switching points.

Note
Potentiometers for adjustment of the modulation limits:



## Note

Usable range for the potentiometers:


## Standards and certificates

C $\epsilon$

- Electromagnetic compatibility EMC (immunity)

2004/108/EC

- Low-voltage directive


ISO 9001: 2008
Cert. 00739


ISO 14001: 2004 Cert. 38233

For use in US/Canada where the power supply lines require a connection facility for flexible conduit, the actuator's product no. includes type suffix «R» (see following example). These products are UL-listed.

Example: SQM40.264R10

## Disposal notes



The unit contains electrical and electronic components and must not be disposed of together with domestic waste.
Local and currently valid legislation must be observed.

Housing
Drive motor

Couplings

## Cam shaft drive

Adjustment of switching points

Position indicator

Electrical connections

Gear train

Drive shaft
Actuator fixing

- Housing parts made of die-cast aluminium
- Covers made of impact-proof and heat-resistant plastic
- Stall-proof synchronous motor
- Shaft can be disengaged from motor by coupling (pressing coupling pin «K1»)
- Automatic reengagement
- Disengagement of drive shaft / motor by pressing coupling pin «K1»

- Non-reactive gear
- With adjustable cams
- Scales beside the cams indicate the angle of the switching point
- Internally
- Scale $0 . . .90^{\circ}$ at the base of the cam assembly
- Scale range to direction of rotation with arrow and «R» or «L» marked
- RAST3.5 screw terminals are enclosed, depending on the PCB variant
- RAST5 screw terminals are enclosed, depending on the PCB variant
- Optional: Insulation displacement connectors
- Wiring through connecting cover
- Easy insertion of cables through large openings in the housing
- Maintenance-free gearwheels and bearings
- Different shaft versions available
- Fixing holes at housing bottom (drive shaft side), like SQM45.../SQM48... with screws M5 or, alternatively, SQM10.../SQM20... front mounting with self-tapping screws M5

Type summary (other types on request)

| Product no. |  | ion tion | Torque | U 든 늘 U | $\begin{aligned} & \underset{y}{0} \\ & \underset{\sim}{\infty} \end{aligned}$ | P <br>  | B <br>  |  | $\begin{aligned} & \frac{\underset{\sigma}{0}}{\omega} \\ & \underset{\sim}{0} \end{aligned}$ | Shaft no. | Re <br> v <br> ? | onal ion の | Ope <br> vo $\begin{aligned} & \text { B } \\ & \text { N} \\ & \stackrel{U}{4} \end{aligned}$ | ting ge <br> Z N్ Ũ | Pot $\begin{aligned} & \frac{0}{O} \\ & \stackrel{=}{\bar{\omega}} \end{aligned}$ | ntioer <br> 0 0 0 0 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SQM40.141A21 | $\bigcirc$ |  | 5Nm/15s | $\bigcirc$ |  |  |  | 3 |  | 1 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.144R11 | $\bigcirc$ |  | $5 \mathrm{Nm} / 15 \mathrm{~s}$ | $\bigcirc$ |  |  |  | 3 |  | 4 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.145A21 | $\bigcirc$ |  | $5 \mathrm{Nm} / 15 \mathrm{~s}$ | $\bigcirc$ |  |  |  | 3 |  | 5 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.145R11 | $\bigcirc$ |  | 5Nm/15s | $\bigcirc$ |  |  |  | 3 |  | 5 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.161A20 | $\bigcirc$ |  | 5Nm/15s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 1 | $\bigcirc$ |  |  | $\bigcirc$ |  |  |
| SQM40.164R11 | $\bigcirc$ |  | 5Nm/15s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 4 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.165A20 | $\bigcirc$ |  | $5 \mathrm{Nm} / 15 \mathrm{~s}$ |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 5 | $\bigcirc$ |  |  | $\bigcirc$ |  |  |
| SQM40.165A21 | - |  | 5Nm/15s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 5 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.165R11 | $\bigcirc$ |  | 5Nm/15s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 5 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.171A20 | $\bigcirc$ |  | $5 \mathrm{Nm} / 15 \mathrm{~s}$ |  | $\bigcirc$ |  | $\bigcirc$ | 5 | 1 | 1 | $\bigcirc$ |  |  | $\bigcirc$ |  |  |
| SQM40.174R10 | $\bigcirc$ |  | 5Nm/15s |  | $\bigcirc$ |  | $\bigcirc$ | 5 | 1 | 4 |  | $\bigcirc$ | $\bigcirc$ |  |  |  |
| SQM40.175A21 | $\bigcirc$ |  | 5Nm/15s |  | $\bigcirc$ |  | $\bigcirc$ | 5 | 1 | 5 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.241A11 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 1 | $\bigcirc$ |  | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.241R11 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 1 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.241A21 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 1 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.244A21 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 4 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.244R11 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 4 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.245A11 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 5 | $\bigcirc$ |  | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.245A21 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 5 | $\bigcirc$ |  |  | $\bigcirc$ | - |  |
| SQM40.245R11 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 5 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.247A21 | $\bigcirc$ |  | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 7 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.261A11 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 1 | $\bigcirc$ |  | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.261R11 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 1 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.261A20 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 1 | $\bigcirc$ |  |  | $\bigcirc$ |  |  |
| SQM40.261A21 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 1 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.261A22 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 1 | $\bigcirc$ |  |  | $\bigcirc$ |  | $\bigcirc$ |
| SQM40.264A21 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 4 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.264R11 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 4 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.265A11 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 5 | $\bigcirc$ |  | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.265A21 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 5 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |
| SQM40.265R11 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 5 |  | $\bigcirc$ | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM40.265A20 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 5 | $\bigcirc$ |  |  | $\bigcirc$ |  |  |
| SQM40.267A20 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 7 | $\bigcirc$ |  |  | $\bigcirc$ |  |  |
| SQM40.271A20 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ |  | $\bigcirc$ | 5 | 1 | 1 | $\bigcirc$ |  |  | $\bigcirc$ |  |  |
| SQM40.271R10 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ |  | $\bigcirc$ | 5 | 1 | 1 |  | $\bigcirc$ | $\bigcirc$ |  |  |  |
| SQM40.274R10 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ |  | $\bigcirc$ | 5 | 1 | 4 |  | - | $\bigcirc$ |  |  |  |
| SQM40.275A20 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ |  | $\bigcirc$ | 5 | 1 | 5 | $\bigcirc$ |  |  | $\bigcirc$ |  |  |
| SQM40.275A21 | $\bigcirc$ |  | 10Nm/30s |  | $\bigcirc$ |  | $\bigcirc$ | 5 | 1 | 5 | $\bigcirc$ |  |  | $\bigcirc$ | $\bigcirc$ |  |

Type summary (cont'd) (other types on request)

| Product no. | Direction of rotation |  | Torque |  | $$ |  | B <br>  |  | $\begin{aligned} & \stackrel{\underset{\omega}{0}}{\stackrel{1}{\infty}} \\ & \hline \end{aligned}$ | Shaft no. |  |  | Operating voltage |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SQM41.141A21 |  | $\bigcirc$ | 5Nm/15s | $\bullet$ |  |  |  | 3 |  | 1 | $\bullet$ |  |  | $\bullet$ | $\bullet$ |  |
| SQM41.144R11 |  | $\bullet$ | 5Nm/15s | $\bullet$ |  |  |  | 3 |  | 4 |  | $\bullet$ | $\bullet$ |  | $\bullet$ |  |
| SQM41.145A21 |  | $\bigcirc$ | 5Nm/15s | $\bigcirc$ |  |  |  | 3 |  | 5 | $\bullet$ |  |  | $\bullet$ | $\bigcirc$ |  |
| SQM41.145R11 |  | $\bullet$ | 5Nm/15s | $\bullet$ |  |  |  | 3 |  | 5 |  | - | - |  | $\bullet$ |  |
| SQM41.164R11 |  | $\bullet$ | 5Nm/15s |  | - | $\bullet$ |  | 6 |  | 4 |  | $\bullet$ | $\bullet$ |  | $\bullet$ |  |
| SQM41.165R11 |  | $\bullet$ | 5Nm/15s |  | - | $\bullet$ |  | 6 |  | 5 |  | - | $\bigcirc$ |  | $\bullet$ |  |
| SQM41.174R10 |  | $\bigcirc$ | 5Nm/15s |  | - |  | $\bullet$ | 5 | 1 | 4 |  | $\bigcirc$ | $\bigcirc$ |  |  |  |
| SQM41.241A11 |  | $\bigcirc$ | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 1 | $\bullet$ |  | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM41.241R11 |  | $\bullet$ | 10Nm/30s | $\bullet$ |  |  |  | 3 |  | 1 |  | $\bullet$ | $\bigcirc$ |  | $\bullet$ |  |
| SQM41.241A21 |  | $\bullet$ | $10 \mathrm{Nm} / 30 \mathrm{~s}$ | $\bullet$ |  |  |  | 3 |  | 1 | $\bullet$ |  |  | $\bigcirc$ | $\bullet$ |  |
| SQM41.244A21 |  | $\bigcirc$ | 10Nm/30s | $\bigcirc$ |  |  |  | 3 |  | 4 | $\bigcirc$ |  |  | $\bullet$ | $\bigcirc$ |  |
| SQM41.244R11 |  | $\bullet$ | 10Nm/30s | $\bullet$ |  |  |  | 3 |  | 4 |  | $\bullet$ | $\bullet$ |  | $\bullet$ |  |
| SQM41.245A11 |  | $\bigcirc$ | 10Nm/30s | $\bullet$ |  |  |  | 3 |  | 5 | $\bullet$ |  | - |  | $\bullet$ |  |
| SQM41.245A21 |  | - | $10 \mathrm{Nm} / 30 \mathrm{~s}$ | $\bullet$ |  |  |  | 3 |  | 5 | $\bullet$ |  |  | - | - |  |
| SQM41.245R11 |  | $\bigcirc$ | 10Nm/30s | $\bullet$ |  |  |  | 3 |  | 5 |  | $\bigcirc$ | $\bigcirc$ |  | $\bullet$ |  |
| SQM41.261A11 |  | $\bullet$ | $10 \mathrm{Nm} / 30 \mathrm{~s}$ |  | $\bigcirc$ | $\bullet$ |  | 6 |  | 1 | $\bullet$ |  | $\bigcirc$ |  | $\bullet$ |  |
| SQM41.261R11 |  | $\bullet$ | 10Nm/30s |  | $\bigcirc$ | $\bigcirc$ |  | 6 |  | 1 |  | - | $\bigcirc$ |  | $\bigcirc$ |  |
| SQM41.261A21 |  | - | $10 \mathrm{Nm} / 30 \mathrm{~s}$ |  | - | $\bigcirc$ |  | 6 |  | 1 | $\bullet$ |  |  | $\bullet$ | $\bullet$ |  |
| SQM41.264A21 |  | $\bullet$ | 10Nm/30s |  | $\bullet$ | $\bullet$ |  | 6 |  | 4 | $\bullet$ |  |  | $\bullet$ | $\bullet$ |  |
| SQM41.265R11 |  | $\bullet$ | 10Nm/30s |  | - | $\bigcirc$ |  | 6 |  | 5 |  | $\bigcirc$ | $\bullet$ |  | $\bullet$ |  |
| SQM41.267A21 |  | $\bullet$ | $10 \mathrm{Nm} / 30 \mathrm{~s}$ |  | - | $\bullet$ |  | 6 |  | 7 | $\bullet$ |  |  | $\bullet$ | $\bullet$ |  |
| SQM41.271R10 |  | $\bullet$ | 10Nm/30s |  | $\bullet$ |  | $\bullet$ | 5 | 1 | 1 |  | $\bullet$ | - |  |  |  |
| SQM41.274R10 |  | - | 10Nm/30s |  | - |  | $\bigcirc$ | 5 | 1 | 4 |  | $\bullet$ | - |  |  |  |
| SQM41.275A21 |  | $\bullet$ | $10 \mathrm{Nm} / 30 \mathrm{~s}$ |  | $\bullet$ |  | $\bullet$ | 5 | 1 | 5 | $\bullet$ |  |  | $\bullet$ | $\bullet$ |  |

Note
Not all types of actuators are available ex stock. Additional versions are available on request.

Drive shafts:

| Type of drive shaft | Max. <br> torque | Shaft no. |
| :--- | :---: | :---: |
| $\varnothing \mathbf{1 0 ~ m m}$, woodruff key as per DIN 6888 | 10 Nm | 1 |
| $\square 9.5 \mathrm{~mm}$, equivalent to drive shaft of Honeywell Mod. III | 10 Nm | 4 |
| $\varnothing 10 \mathrm{~mm}$ D type shaft, compatible with SQM45... | 10 Nm | 5 |
| $\varnothing \mathbf{1 4 ~ m m}$ with parallel key as per DIN 6885, compatible with SQM48... | 10 Nm | 7 |

- Woodruff key or parallel key
- Connectors depending on the PCB variant


## Front cover

(on request)
For making the connections for the power supply lines

- For 1/2" NPT protective sleeve
- For metric cable gland


## Note

Connecting covers are used depending on the application. The actuators come with the covers prefitted.

## Terminal kits

- For replacement
- For SQM4x.x4x.xxx

AGA45.4

- For SQM4x.x6x.xxx and SQM4x.x7x.xxx

AGA45.6

Technical Data

| General unit data | Operating voltage <br> - SQM4x.xxxA1... <br> - SQM4x.xxxA2... <br> - SQM4x.xxxR1... <br> - SQM4x.xxxR2... | AC 120 V-15\%/+10\% <br> AC $230 \mathrm{~V}-15 \% /+10 \%$ <br> AC $120 \mathrm{~V}-15 \% /+10 \%$ <br> AC $230 \mathrm{~V}-15 \% /+10 \%$ |
| :---: | :---: | :---: |
|  | Operating frequency | $50 . . .60 \mathrm{~Hz} \pm 6 \%$ |
|  | Drive motor | Synchronous motor |
|  | Power consumption | 10 VA |
|  | Operating angle | Adjustable between 0 and max. $90^{\circ}$ |
|  | Mounting position | Optional |
|  | Degree of protection | IP66/Nema 4 |
|  | External overload fuse | Max. 6,3 AT (slow) to DIN EN 60127/2-5 |
|  | Cable entry | $2 \times$ M16 without thread or $2 \times 1 / 2 "$ NPT thread |
|  | Direction of rotation | Facing the shaft end: counterclockwise or clockwise |
|  | Torque <br> (Holding torque $=$ driving torque $\times 50 \%$ ) | 5 or 10 Nm , depending on type ${ }^{1)}$ For torques refer to nominal operating conditions |
|  | Running time | 15 s and 30 s, depending on type ${ }^{1)}$ |
|  | End and auxiliary switches <br> - Type <br> - Switching voltage <br> - Switching capacity | To DIN 41636 AC $24 . . .250 \mathrm{~V}$ $1 \mathrm{~A}, \mathrm{AC} 250 \mathrm{~V}$ |
|  | Number of end switches | 2 |
|  | Number of auxiliary switches | Max. 4 |
|  | Drive shaft | Supplied as standard, not replaceable |
|  | Weight | Approx. 2 kg |
|  | 1) At 60 Hz frequency, running times are about | \% shorter and torques lower by the same rate. |
| Analog inputs | General |  |
|  | Linearity | <5\% |
|  | Control range | 0... $90^{\circ}$ |
|  | Voltage setpoint | DC 2... 10 V |
|  | X1-1 (U-IN), X1-2 (GND) |  |
|  | - Umin | DC 2 (0) V |
|  | - Umax | DC 10 V |
|  | Input impedance | $\geq 5 \mathrm{k} \Omega$ |
|  | Current setpoint | DC 4... 20 mA |
|  | X1-3 (I-IN), X1-2 (GND) |  |
|  | -Imin | DC 4 (0) mA |
|  | - Imax | DC 20 mA |
|  | Input impedance | $\leq 500 \Omega$ |
|  | Impedance setpoint | 0... $135 \Omega$ |
|  | X1-4, X1-5, X1-6 (GND) |  |
|  | - RNominal | $135 \Omega \pm 5 \%$ |


| Conductive plastic potentiometer | Operating voltage | DC 10 V |
| :---: | :---: | :---: |
|  | Permissible hysteresis | $0,2 \%$ of $90^{\circ}$ or $135^{\circ}$ |
|  | Total resistance tolerance | $\pm 20 \%$ |
|  | Effective angular rotation | $90^{\circ}$ or $135^{\circ}$ |
|  | Terminal strip | Triple-pole |
|  | For cross-sectional areas of | 0,5... $1 \mathrm{~mm}^{2}$ |
|  | Wiper current rating | Max. $100 \mu \mathrm{~A}$ |
|  | Transfer resistance of wiper contact | Max. Rü $\leq 100 \Omega$ |
|  | Linearity (referred to Rges = $1000 \Omega$ ) | $\pm 1 \%$ |
|  | Smoothness (alpha $=10^{\circ}$ ) / microlinearity | <0,1\% |
|  | Life cycle | Approx. 2 million switching cycles |
| For use in North America | Cross-sectional area of the power supply lines |  |
|  | $\begin{aligned} & \text { For SQM4x.x6.../SQM4x.x7... (X1)/(X2)/ } \\ & \text { (X3), SQM4x.4... (X2) } \end{aligned}$ | Class 1 <br> Min. AWG 16 <br> Suited for $105^{\circ} \mathrm{C}$ <br> Max. $2.5 \mathrm{~mm}^{2}$ or AWG 14 |
|  | For SQM4x.x4... (X1) | Class 2 <br> Min. AWG 22 <br> Suited for $105^{\circ} \mathrm{C}$ <br> Max. $1 \mathrm{~mm}^{2}$ or AWG 18 |
| Environmental conditions | Storage | DIN EN 60721-3-1 |
|  | Climatic conditions | Class 1K3 |
|  | Mechanical conditions | Class 1M2 |
|  | Temperature range | $-20 . . .60{ }^{\circ} \mathrm{C}$ |
|  | Humidity | <95\% r.h. |
|  | Transport | DIN EN 60721-3-2 |
|  | Climatic conditions | Class 2K3 |
|  | Mechanical conditions | Class 2M2 |
|  | Temperature range | $-20 . . .60{ }^{\circ} \mathrm{C}$ |
|  | Humidity | <95\% r.h. |
|  | Operation | DIN EN 60721-3-3 |
|  | Climatic conditions | Class 3K5 |
|  | Mechanical conditions | Class 3M4 |
|  | Temperature range | $-20 . . .60{ }^{\circ} \mathrm{C}$ |
|  | Humidity | <95\% r.h. |



Range adjustment

Adjust the range of the analog signal to match the switch positions (min. and max. position):

1. Set cam I to the required high-fire position (e.g. $85^{\circ}$; position is indicated on the scale next to the cam).
2. Set cam $V$ to the required low-fire position (e.g. $20^{\circ}$ ).
3. Preset the signal at the analog input according to the required high-fire position (e.g. 20 mA ).
4. Turn the potentiometer for maximum angular rotation
a) clockwise, if the actuator has not yet reached its maximum angular rotation, or
b) counterclockwise until the actuator starts
5. Preset the signal at the analog input according to the low-fire position (e.g. 4 mA ).

6 . Turn the potentiometer for minimum angular rotation
a) counterclockwise, if the actuator has not yet reached its minimum angular rotation, or
b) clockwise until the actuator starts

Modulation always takes place between high- and low-fire.
Also, it is possible to define a closed position or a separate ignition position by setting cam VI (independent of cam V , e.g. for defining a position higher than the low-fire position).


Connection terminals (cont'd)
SQM4x.x6xxx
3 -position version with 2 end switches and 4 auxiliary switches


SQM4x.x7xxxx
2-position version with 2 end switches and 3 auxiliary switches


| Mains voltage terminals |  | Design |  |
| :--- | :--- | :--- | :--- |
| X3-1 | AUX (VI) NO | Output | AC 120 V/AC 230 V <br> max. 1 A |
| X3-2 | AUX (VI) NC | Output | AC 120 V/AC 230 V <br> max. 1 A |
| X3-3 | AUX (VI) | Input | AC 120 V/AC 230 V |
| X2-1 | Mains voltage | Input | AC 120 V/AC 230 V |
| X2-2 | Opening/closing <br> (changeover switch) | Input | AC 120 V/AC 230 V |
| X2-3 | Open position reached | Output | AC 120 V/AC 230 V <br> max. 1 A |
| X2-4 | Closed position reached | Output | AC 120 V/AC 230 V <br> max. 1 A |
| X2-5 | Ignition position reached | Output | AC 120 V/AC 230 V <br> max. 1 A |
|  |  |  | AC 120 V/AC 230 V |
| X1-1 | Startup in ignition position | Input | Output |
| X1-2 | AUX (IV) NO 120 V/AC 230 V |  |  |
| max. 1 A |  |  |  |

Example for SQM40... (CCW)


Example for SQM41... (CW)


Note!
The setting of the switch position must be checked.

SQM4x.x4...

| Electronic version |  | Preadjustment |
| :--- | :--- | :---: |
| Cam I | High-fire | $90^{\circ}$ |
| Cam II | Not used | --- |
| Cam III | Not used | --- |
| Cam IV | Not used | --- |
| Cam V | Low-fire | $10^{\circ}$ |
| Cam VI | OFF/ignition | $0^{\circ}$ |

SQM4x.x6...

| 3-position version |  | Preadjustment |
| :--- | :--- | :---: |
| Cam I | High-fire | $90^{\circ}$ |
| Cam II | OFF/low-fire | $0^{\circ}$ |
| Cam III | Ignition position | $10^{\circ}$ |
| Cam IV | Auxiliary switch | $30^{\circ}$ |
| Cam V | Auxiliary switch | $30^{\circ}$ |
| Cam VI | Auxiliary switch | $30^{\circ}$ |

SQM4x.x7...

| 2-position version |  | Preadjustment |
| :--- | :--- | :---: |
| Cam I | High-fire | $90^{\circ}$ |
| Cam II | OFF/low-fire | $0^{\circ}$ |
| Cam III | Ignition position | $10^{\circ}$ |
| Cam IV | Auxiliary switch | $30^{\circ}$ |
| Cam V | Not used | --- |
| Cam VI | Auxiliary switch | $30^{\circ}$ |

## Dimensions in mm

SQM40.../SQM41...


